

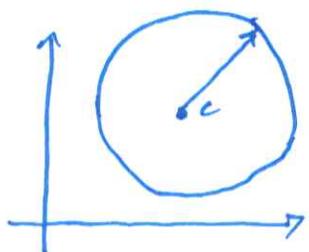
Nov. 21: 3D coordinate systems & Vectors.

1

Reminder: Written HW due Monday after break.

Last time: 3D coord. systems.

Reminder: In 2D, a circle of radius r and center c is the set of all points of distance r away from the point c .



$$\begin{aligned} \text{circle } (\overset{c}{(a,b)}, r) &= \{ (x,y) : |(a,b), (x,y)| = r \} \\ &= \{ (x,y) : \underbrace{(x-a)^2 + (y-b)^2}_{\text{dist. in 2D}} = r^2 \} \end{aligned}$$

In 3D, a sphere (spherical shell) of radius r & ctr. (a,b,c) is the set of all pts. of dist. r from (a,b,c) .

$$\text{Sphere } (a,b,c), r = \{ (x,y,z) : |(a,b,c) \& (x,y,z)| = r \}$$

$$= \{ (x,y,z) : (x-a)^2 + (y-b)^2 + (z-c)^2 = r^2 \}$$

The eq'n of a sphere is $(x-a)^2 + (y-b)^2 + (z-c)^2 = r^2$.

EXAMPLE 1. Find the ctr. & radius of

$$x^2 + y^2 + z^2 + 3x - 4z + 1 = 0.$$

Strategy: complete the square in $x, y, \& z$.

$$[x^2 + 3x] + [y^2] + [z^2 - 4z] = -1$$

→ add $(\frac{3}{2})^2$ to both sides

$$(x+a)^2 = x^2 + 2ax + a^2$$

→ add $(\frac{-4}{2})^2$ to both sides

$$[x^2 + 3x + (\frac{3}{2})^2] + [y^2] + [z^2 - 4z + (\frac{-4}{2})^2] = -1 + (\frac{3}{2})^2 + (\frac{-4}{2})^2$$

$$(x + \frac{3}{2})^2 + (y+0)^2 + (z - \frac{4}{2})^2 = -1 + \frac{9}{4} + 4$$

$$(x + \frac{3}{2})^2 + (y+0)^2 + (z-2)^2 = 3 + \frac{9}{4} = \frac{12+9}{4} = \frac{21}{4}$$

$$(x + \frac{3}{2})^2 + (y+0)^2 + (z-2)^2 = \frac{21}{4}$$

$$(x-a)^2 + (y-b)^2 + (z-c)^2 = r^2 \quad \leftarrow \text{ sphere ctr. at } (a,b,c), \text{ radi. } r$$

For us, $r^2 = \frac{21}{4}$, so $r = \sqrt{\frac{21}{4}} = \frac{\sqrt{21}}{2}$,

and the center is $(-\frac{3}{2}, 0, 2)$.

EXAMPLES (2)

(a) $\{(x,y,z) : x^2 + y^2 + z^2 < 4\}$

(b) $\{(x,y,z) : x^2 + y^2 + z^2 \leq 4\}$

(c) $\{(x,y,z) : x^2 + y^2 + z^2 > 4\}$

(d) $\{(x,y,z) : x^2 + y^2 + z^2 = 4, z \leq 0\}$

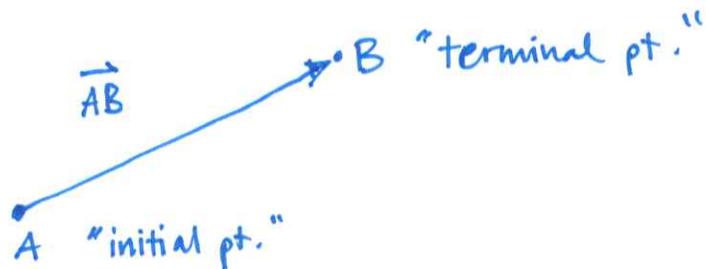
Vectors

3

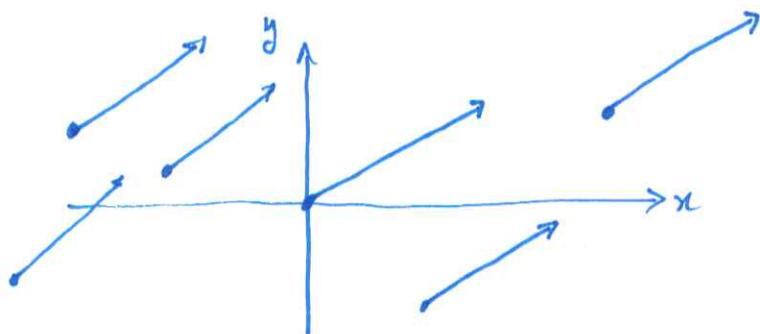
Describe qties. w/ both magnitude and direction, e.g.

- Force
- Displacement
- Velocity

In \mathbb{R}^3 , a vector is graphed as a directed line segment:



Two vectors in \mathbb{R}^3 are "equal" if they have the same magnitude \ni direc'm, regardless of the initial pt.



Typically, the vector \hat{a} at the origin is the one used in w. initial pt.

computations to represent all equal vectors, \ni is said \pm/b in "standard form".

When working with standard vectors, we represent them by giving the (Cartesian) coordinates of the terminal points:

DEF. If \vec{v} is a vector in \mathbb{R}^3 whose std. form has terminus $P(v_1, v_2, v_3)$, then the component form of \vec{v} is given as

$$\vec{v} := \langle v_1, v_2, v_3 \rangle$$